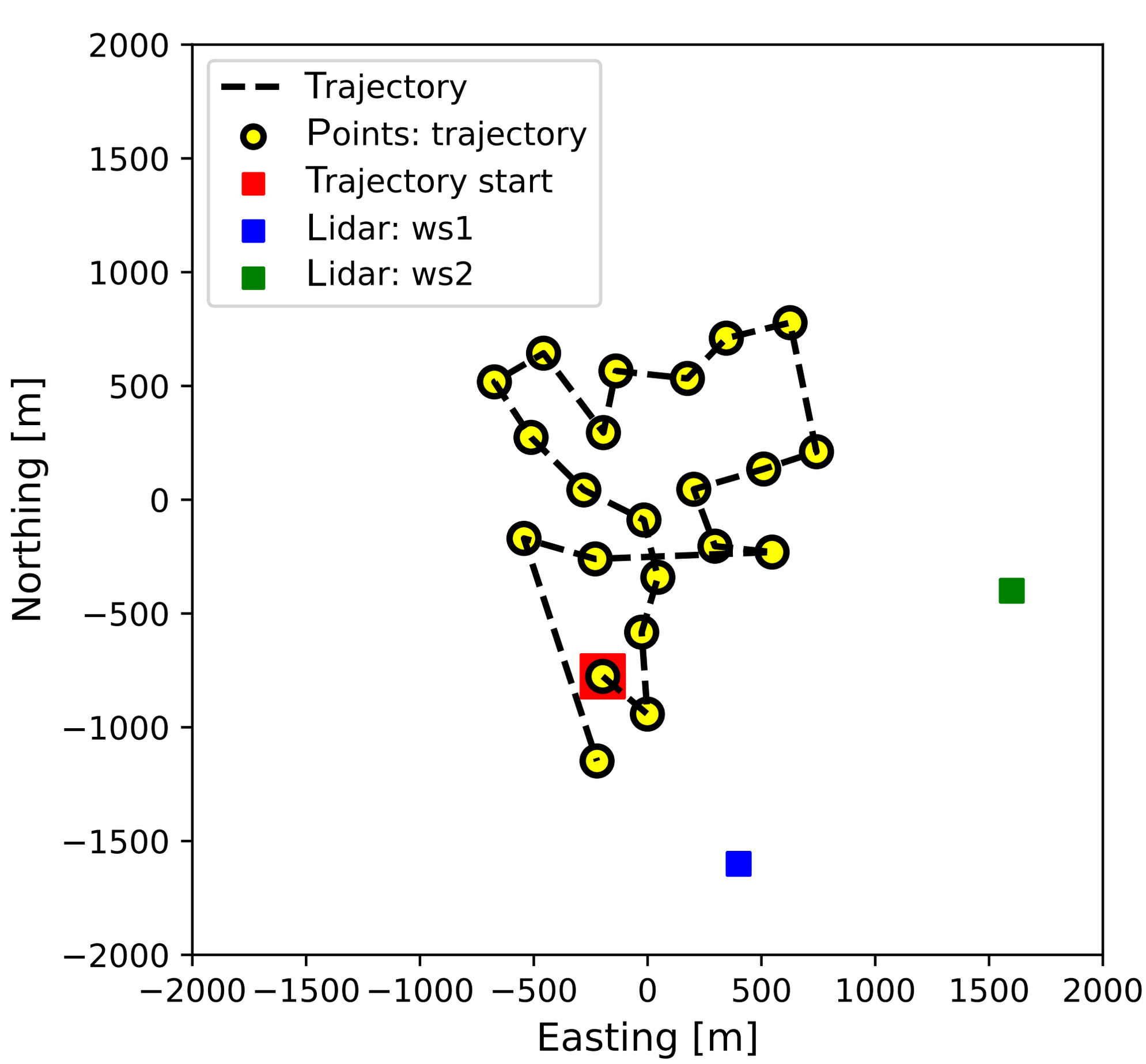
Trajectory
Points: trajectory
Trajectory start
Lidar: ws1
Lidar: ws2
Northing [m]
Easting [m]
2000
1500
1000
500
0
−500
−1000
−1500
−2000
−2000
−1500
−1000
−500
0
500
1000
1500
2000